
Modeling Some Data Communications Functions using Microsoft Excel 5.0

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Features that aid modeling

Complex numbers:

- Make complex, add, subtract, multiply, divide, extract magnitude, phase parts
- extract real, imaginary parts

Fourier transform:

- FFT, IFFT (for integer powers of two only)
- Requires installation of the analysis toolpack

VBA - Visual Basic for Applications:

- Comes installed as a standard part of Excel
- Use to automate tiresome functions:
 - Multiply-Accumulate
 - Pseudo-random number generation

Features that aid modeling, cont'd.

Engineering and Statistical functions:

- Gaussian, uniform, Poisson random number generators

- Evaluation of Gaussian, Poisson PDF's.

- Evaluation of Gaussian PDF integral

 - Complementary error function - erfc()

- Trigonometric functions

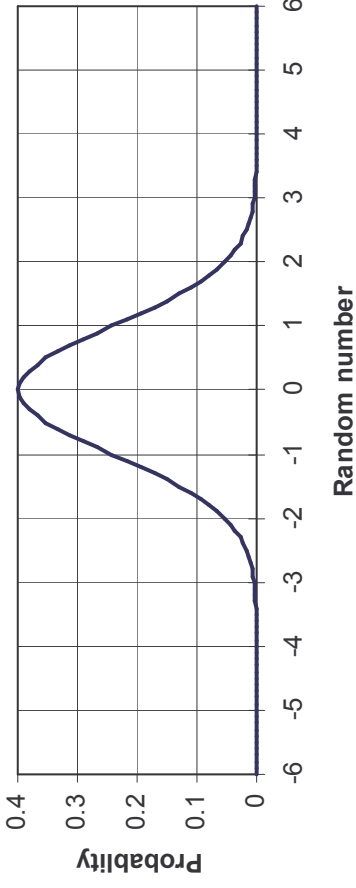
 - Sin, Cos, Tan, Sinh, Cosh, Tanh

Good graphing capabilities

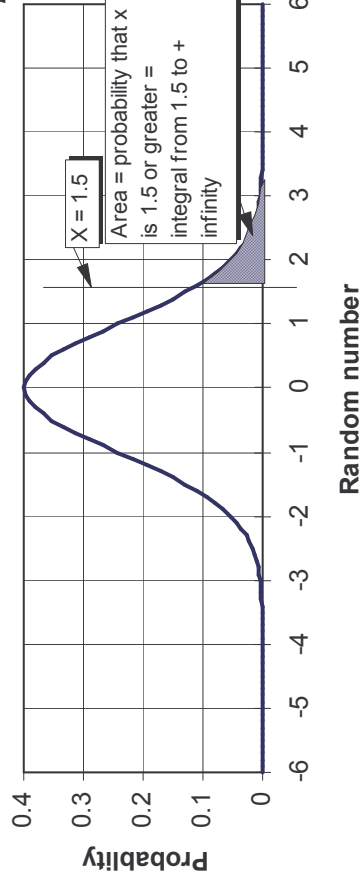
- Log, linear, multivariable, x-vs.-y, etc.

BER vs. AWGN

Probability density of AWGN noise:
$$P(x) = \frac{1}{\sqrt{2\pi}} \exp\left[-\frac{x^2}{2}\right]$$



Cumulative density of AWGN noise:
$$Error(x) = \int_{-\infty}^x \frac{1}{\sqrt{2\pi}} \exp\left[-\frac{x^2}{2}\right] dx$$



BER generation vs. AWGN

SNR / bit, db.	0	0.5	1	1.5	2	2.5	3
SNR/bit, ratio	1	1.122018	1.258925	1.412538	1.584893	1.778279	1.995262
2PSK	0.07865	0.067065	0.056282	0.046401	0.037506	0.029655	0.022878
Coherent 2 FSK	0.158655	0.144742	0.130927	0.117318	0.104029	0.09118	0.078896
Noncoherent FSK	0.303265	0.285316	0.266439	0.246741	0.2226368	0.205505	0.184376

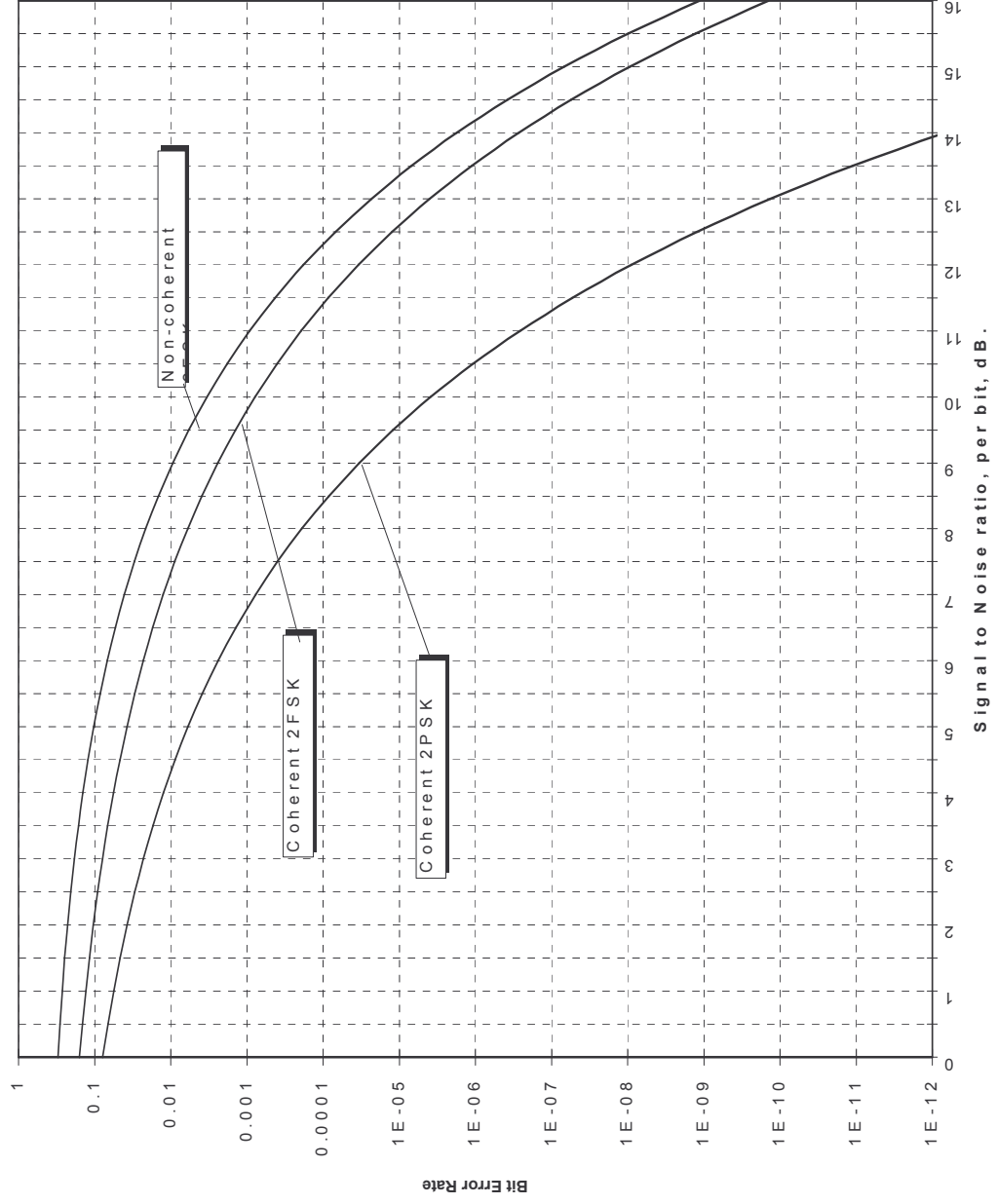
Converting dB. ratio to SNR ratio: $=10^{(C3/10)}$

Converting x to P(x) for 2PSK $=0.5*ERFC(\text{SQRT}(B5))$

Converting x to P(x) for C2FSK $=0.5*ERFC(\text{SQRT}(B5/2))$

Converting x to P(x) for NC2FSK $=0.5*EXP(-B5/2)$

Graphing the results

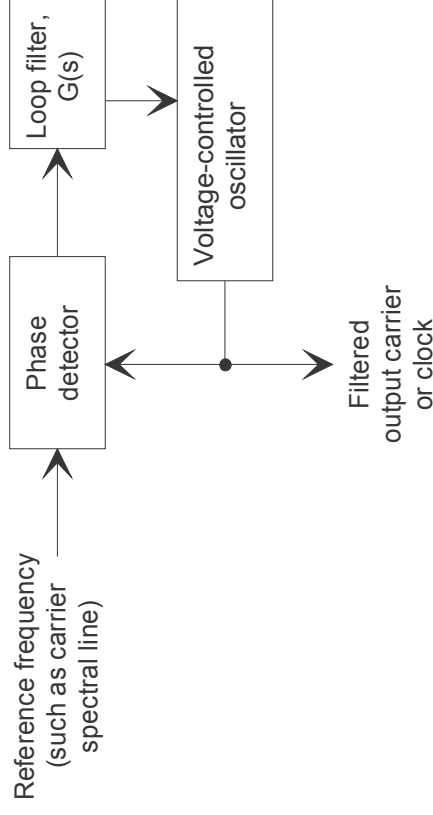


Phase-Locked Loop Analysis

Phase-Locked Loops are useful in clock- and carrier- recovery circuits for digital modems.

Open-loop and Closed-loop responses of the PLL are usually the two basic parameters of interest.

Need to solve for output phase divided by input phase for both cases.



Derivation of closed-loop gain

Write the loop equation: $Out = (In - Out) K_v G(s) \frac{K_f}{s}$

$$Out + Out \left(K_v G(s) \frac{K_f}{s} \right) = In K_v G(s) \frac{K_f}{s}$$

$$Out \left(1 + K_v G(s) \frac{K_f}{s} \right) = In K_v G(s) \frac{K_f}{s}$$

$$\frac{Out}{In} = \frac{K_v G(s) \frac{K_f}{s}}{\left(1 + K_v G(s) \frac{K_f}{s} \right)}$$
$$H(s) = \frac{Out}{In} = \frac{G(s) K_v K_f}{s + G(s) K_v K_f}$$

Calculating the Closed-Loop Response vs. Frequency

Frequency, hertz	0.01	0.012	0.0144	0.01728	0.020736
s	6.2831853	7.5398223	9.04778684	0.1085734	0.1302881
G(s)	9.9984211	9.9977265	9.99672657	9.9952869	9.9932146
KvKfG(s)	628.21932	628.17568	628.112855	628.02240	627.89219
s+KvKfG(s)	628.21932	628.17568	628.112855	628.02240	627.89219
H(s)	1.0000012	1.0000017	1.00000258	1.0000037	1.0000053
mag H(s)	1.000001	1.000002	1.0000026	1.000004	1.000005
phase H(s)	-0.00573	-0.00688	-0.008251	-0.0099	-0.01188
mag H(s), dB.	1.09E-05	1.57E-05	2.254E-05	3.25E-05	4.67E-05

$$s = \text{COMPLEX}(0, 2 * \text{PI}() * \text{B9})$$

$$G(s) = \text{IMDIV}(\$G\$5 * \$G\$6, \text{IMSUM}(\text{B10}, \$G\$6))$$

$$\text{KvKfG}(s) = \text{IMPRODUCT}(\$C\$5, \$C\$6, \text{B11})$$

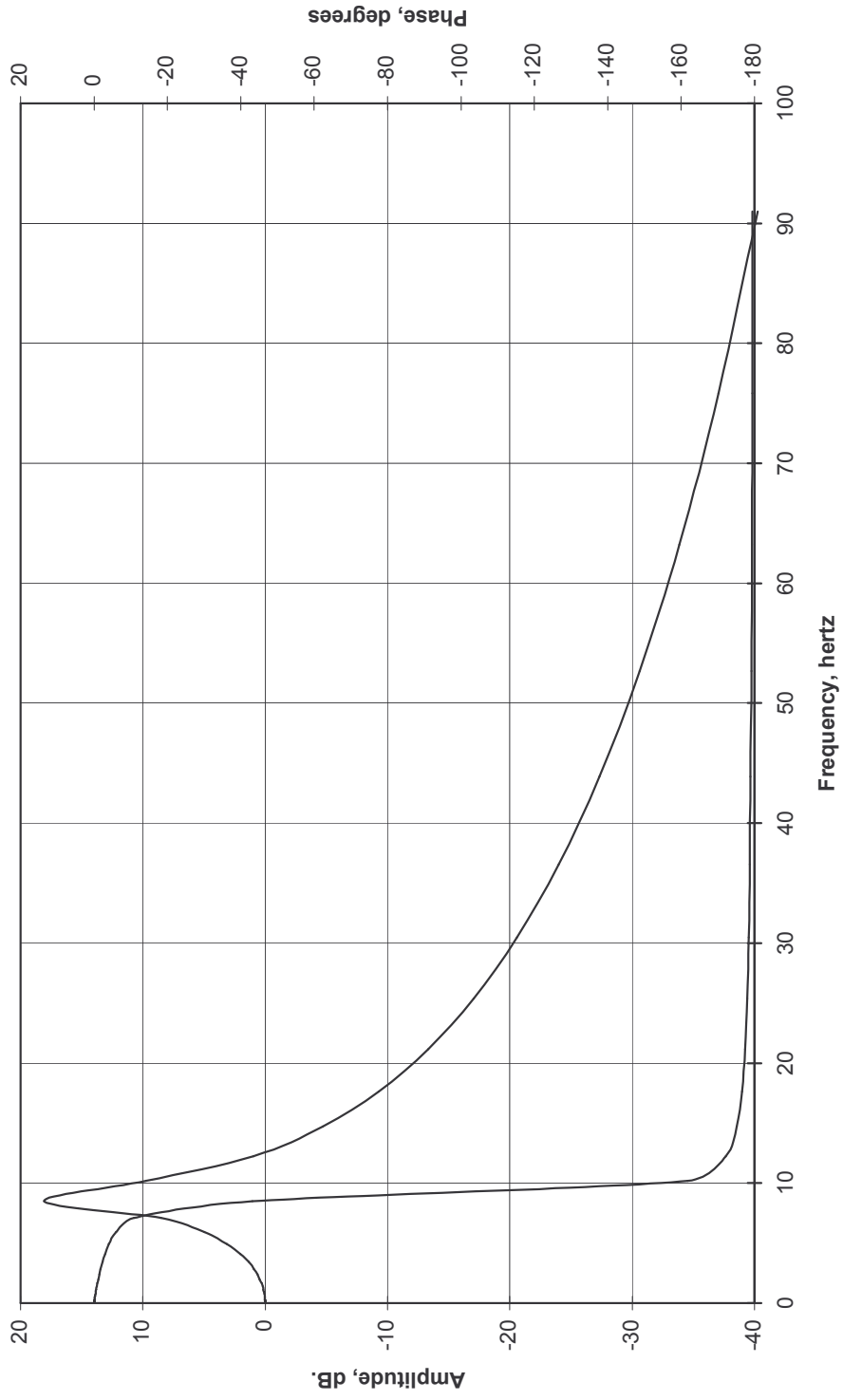
$$s + \text{KvKfG}(s) = \text{IMSUM}(\text{B10}, \text{B12})$$

$$H(s) = \text{IMDIV}(\text{B12}, \text{B13})$$

$$\text{mag } H(s) = \text{IMABS}(\text{B14})$$

Graphing the result

PLL closed loop response
with single pole RC filter



Deriving the Open-Loop Response

Write the transfer function: $Out = In K_v G(s) \frac{K_f}{s}$

$$\frac{Out}{In} = K_v G(s) \frac{K_f}{s}$$

Solve for transfer gain:

$$\frac{Out}{In} = \frac{K_v G(s) K_f}{s}$$

Computing the Transfer Response

Open Loop Respons	-125.64386	-125.63513	-125.62257	-125.60448	-125.57843
Open loop mag, dB	79.99931	78.41539	76.831328	75.24708	73.66255
Open loop phase, de	-90.72	-90.8639	-91.03669	-91.244	-91.4927

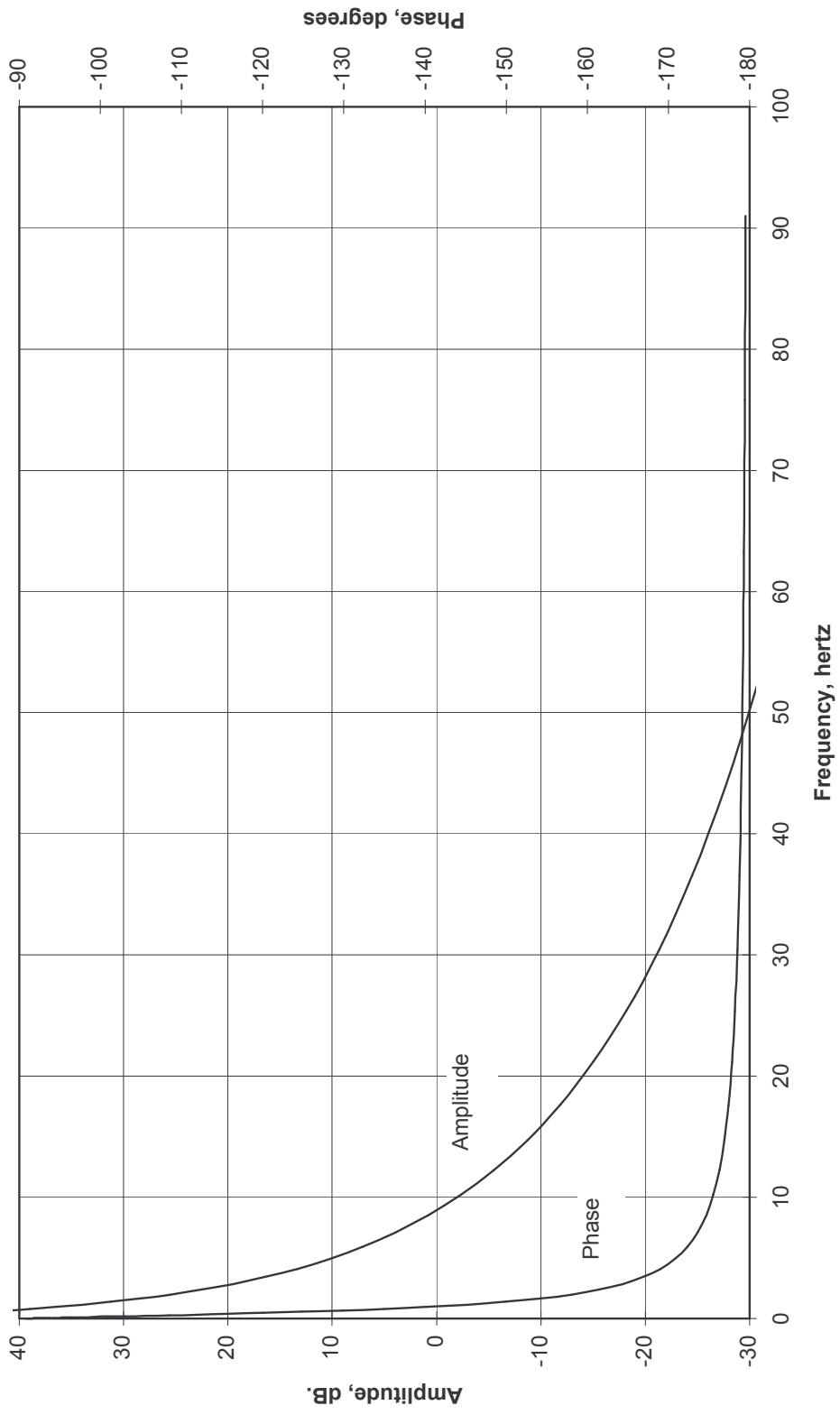
Open Loop Response =IMDIV(B12,B10)

Open loop mag, dB. =20*LOG(IMABS(B18))

Open loop Phase, deg. =IMARGUMENT(B18)*180/PI()

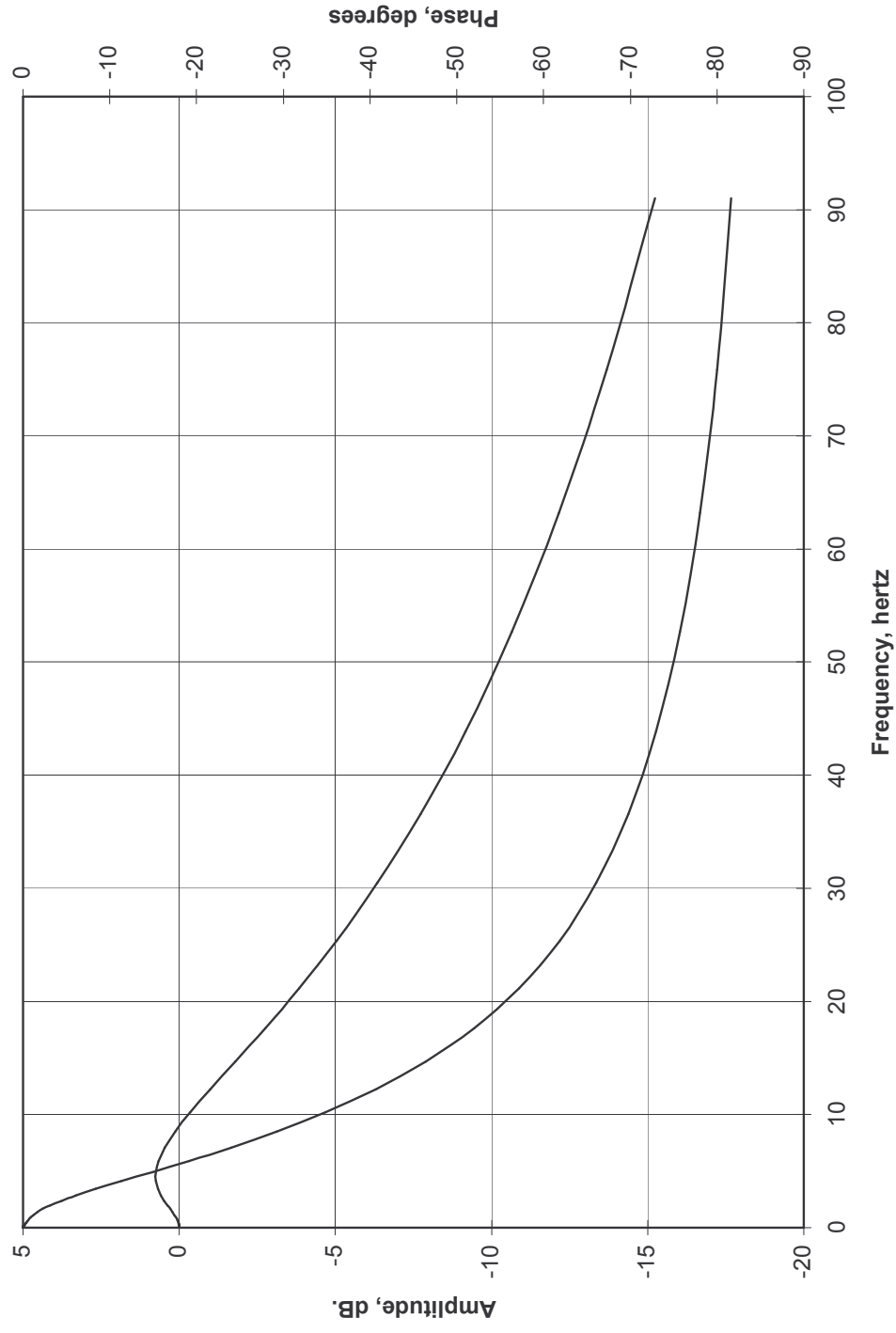
Graphing the Result

Open-loop response of PLL
with lead-lag filter



Closed-Loop Response with Improved Loop Filter

PLL closed-loop response with lead-lag lowpass filter



Eye Pattern vs. Modem Channel Response

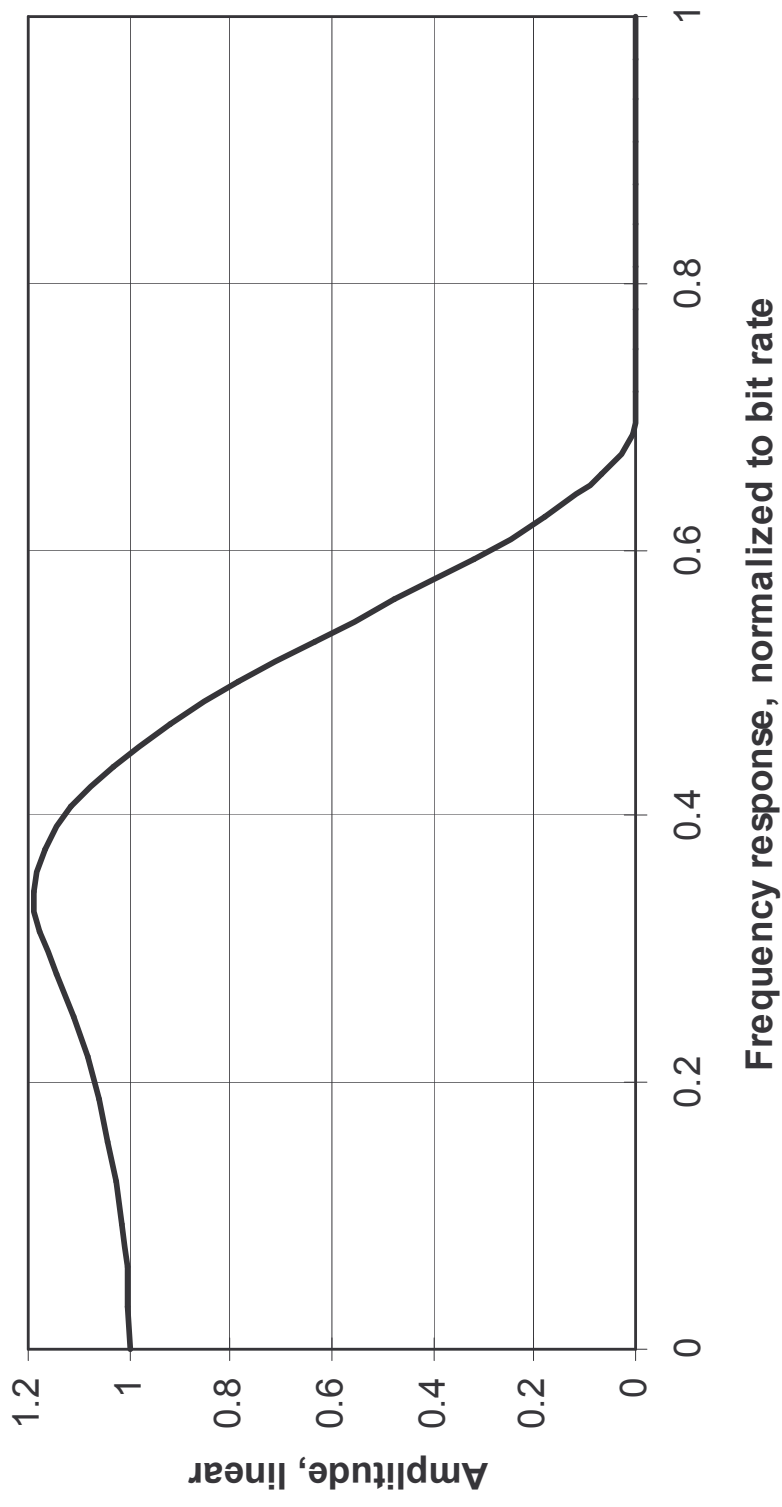
This function is somewhat more complicated than previous examples.

The general procedure is:

1. **Generate channel amplitude/phase response vs. frequency.**
We'll use a raised-cosine function in this example.
2. **Use inverse Fourier transform to generate channel impulse response.** A large amount of over-sampling gives smoother results in the time domain.
3. **Generate pseudo-random data stream.**
4. **Convolve data stream with channel impulse response.** This generates the time-domain filter output with ringing.
5. **Carve up the ringing waveform into 3-bit wide overlapping slices and display against bit periods -- this is the eye pattern.**

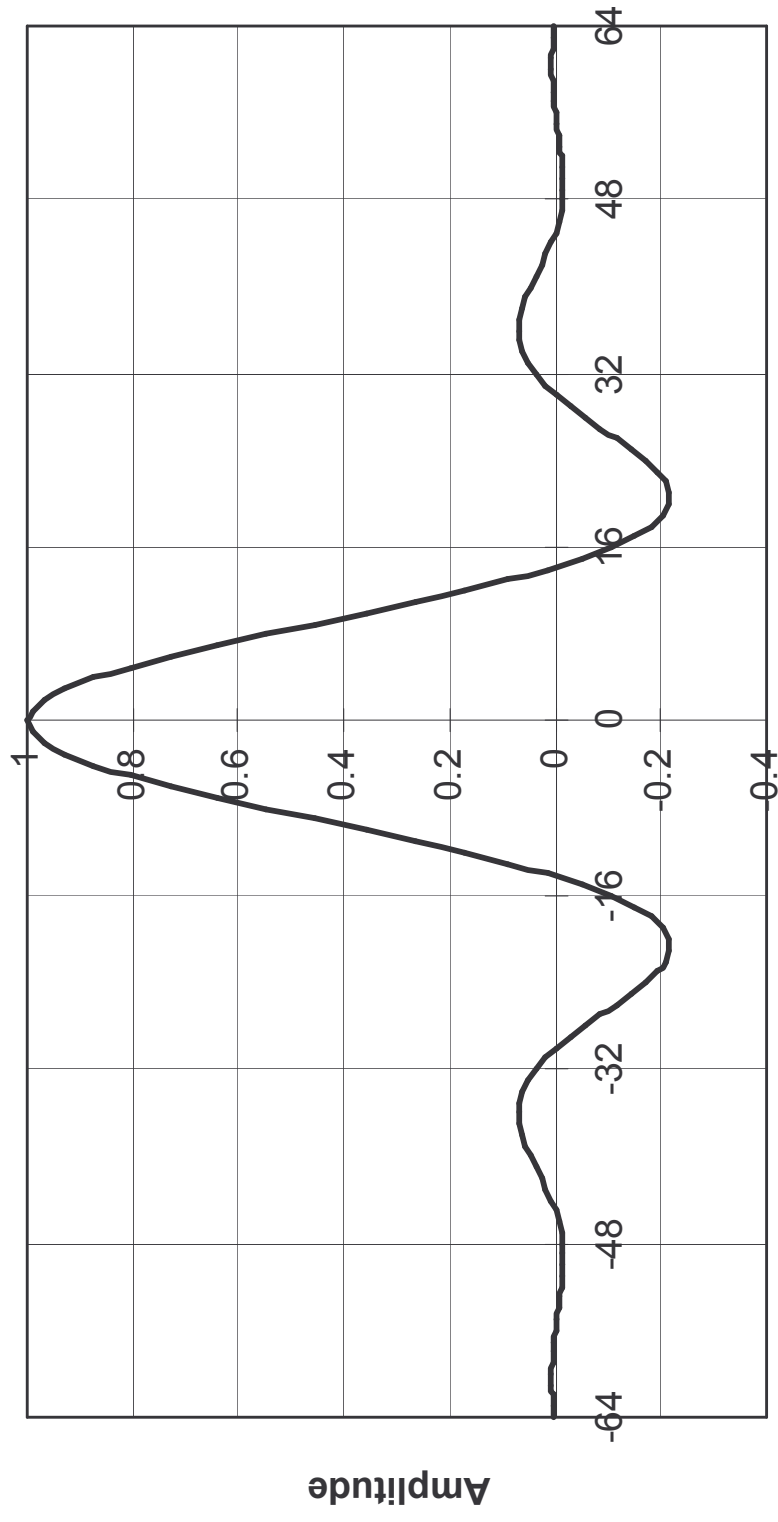
Step 1 - Generate Amplitude vs. Frequency

Frequency response of raised-cosine + sinc-compensated channel



Step 2 - Inverse FFT to Generate Impulse Response

Impulse response of $\alpha=0.4$ sinc-compensated channel



Time, 16 units equal one databit interval

Step 4 - Perform Linear Convolution of Data with Impulse Response

Convolution Integral is:
$$y(t) = \int_{-\infty}^{+\infty} h(\tau)x(t - \tau)d\tau$$

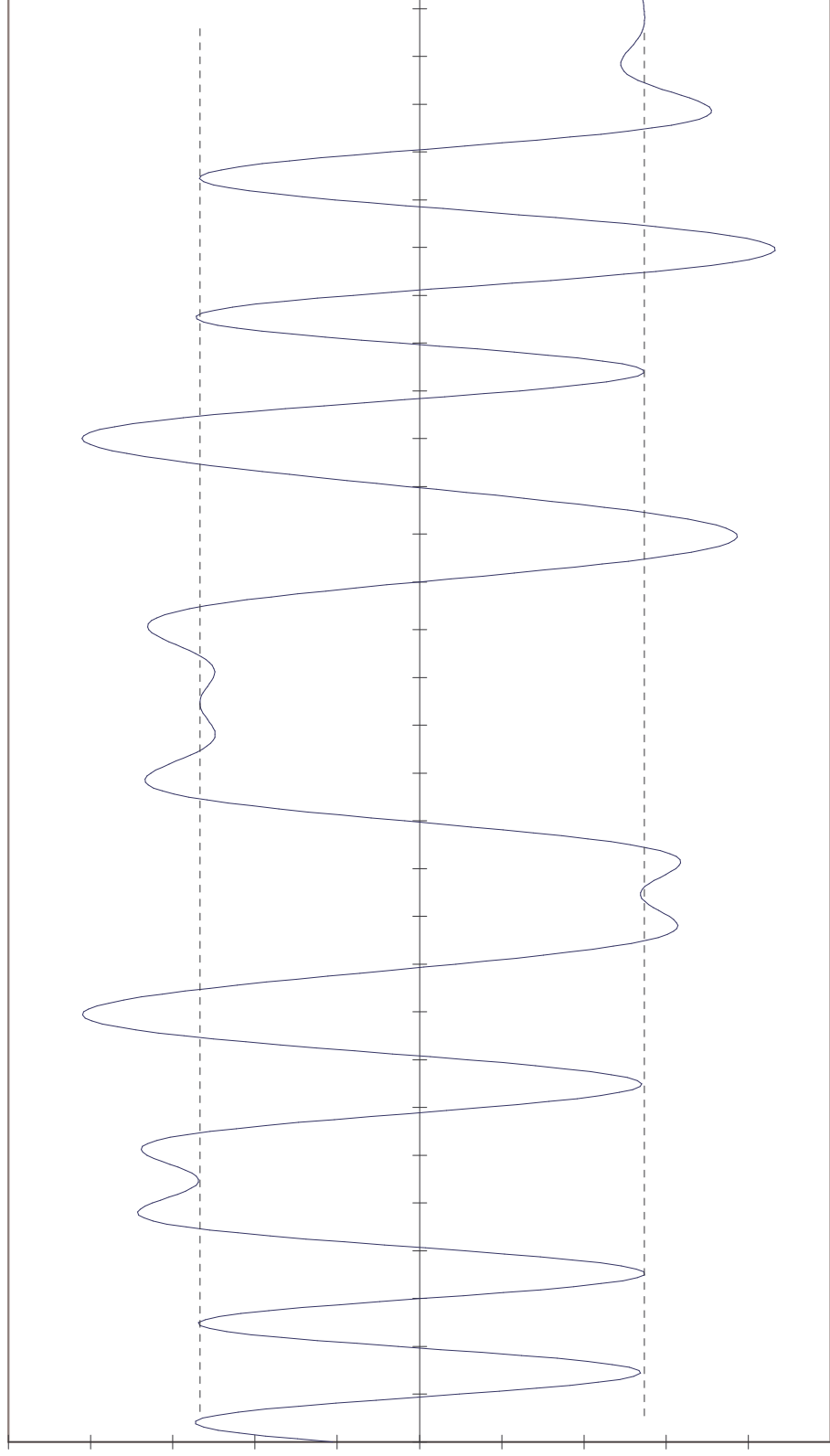
Key to most DSP functions (Convolution, Correlation, Autocorrelation, etc.) is the Multiply-Accumulate kernel. This can be written as an Excel VBA function:

```
' MpyAcum Procedure
' 1/12/95 by Tom McDermott
' Kernel of many DSP routines
' Especially useful for convolution
Function MpyAcum(ImpCellRef, DataCellRef)
    Dim Acum As Single
    lrow = ImpCellRef.Rows.Count
    lcol = ImpCellRef.Columns.Count
    Drow = DataCellRef.Rows.Count
    Dcol = DataCellRef.Columns.Count
    Acum = 0
    For l = 1 To NumCalc
        Acum = Acum + ImpCellRef(l) * DataCellRef(l)
    Next l
    MpyAcum = Acum
End Function
```

=MpyAcum(\$B\$10:\$B\$138,G10:G138)

Graphing the Result gives the Time-Domain Response of the Channel

Time-domain response of $x/x_{in}(x)$ compensated raised-cosine filter
alpha = 0.4, sequence = 2⁵ - 1 PRBS



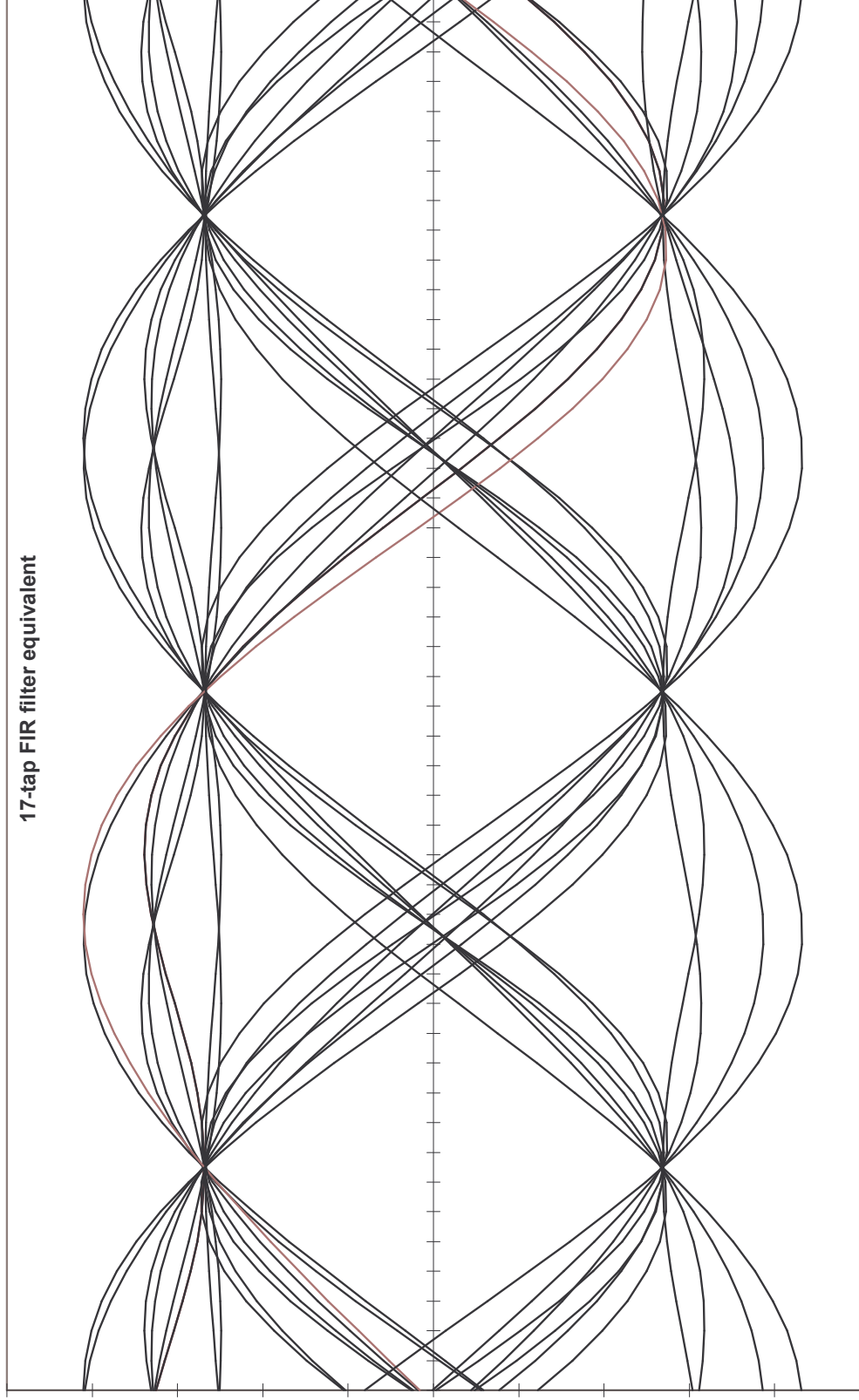
One division equals one bit time

Step 5 - Carve-up the Time-Domain Response into 3-bit wide Pieces

Eye Pattern - Raised cosine + $x/\sin(x)$ compensation

alpha = 0.4, sequence = $2^5 - 1$ PRBS

17-tap FIR filter equivalent



Summary

With the aid of:

**Complex numbers,
Fourier transform,**

**User-definable macros and functions,
and graphical presentation aids.**

**Modern spreadsheets permit the analysis of many data
communications functions.**